



“EV-Power Optimization” (lead MOBIS)
spin-off of “EV-Charging group” (lead FORD)

Goal:

Abstraction of an app for last mile extension based on VSS

EV Power Optimization: Initiator MOBIS

Extend VSS for power management

Choice 1: (read-only or actuator set-value)

Add data points for current data value

e.g. “display brightness level”, later powertrain, HVAC

1a) go for data type “**sensor**” [r]

advantage

power derating is done via actuator settings

1b) go for data type “**actuator**” [rw]

advantage

Power might be used also as a set value

for power derating-SW below VSS

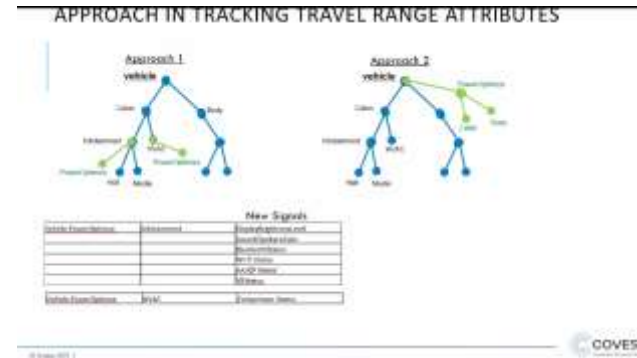
VSS derating set-value can only be a recommendation to the low level SW below api (lowest brigdness is not “0”)

RB recommendation

Choice 2: Where allocate to new data?

2a) new power data under each branch
close link to component

2b) new power branch
condensed view



2c) Add **meta** data “power” to existing component

→ as a dynamic meta data [r]

→ as read-only “power” or “current”

Advantage: no extension of VSS tree

Disadvantage: no set value possible

some values might not map to individual VSS-data points

~100 components/vehicle -> additional points tbc

EV Power Optimization: Initiator MOBIS

Split reading sensors value and the set-value

Set-value (actuator) – recommendation to component, only:

- Degradation system state = mode for each main branch (powertrain, body, Cabin, ADAS, Chassis ...) : [1...10] with [power system state “1”: lowest power possible, ..., “10” max consumption allowed]
- Or Power level-value for each domain (= main branch) [0...100%] with [0% lowest power possible, ... , 100% max power consumption]

RB recommendation

Each component can overrule this power mode recommendation according local needs (legal, safety,...)

For later (if abstractable from different vehicle architectures)

- Dyn. Power [W] (Read for each component - RB-preferred)
- Dyn. Current [A] ← s. like CAAM
- s. also vHAL (e.g. μ P power)

In a second step, based on use-cases