

Data-Centric Communications and DDS COVESA AMM

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COVESA

Accelerating the future of connected vehicles



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RTI at the Core of Innovation and Standarization





OBJECT MANAGEMENT GROUP



AUTOSAR



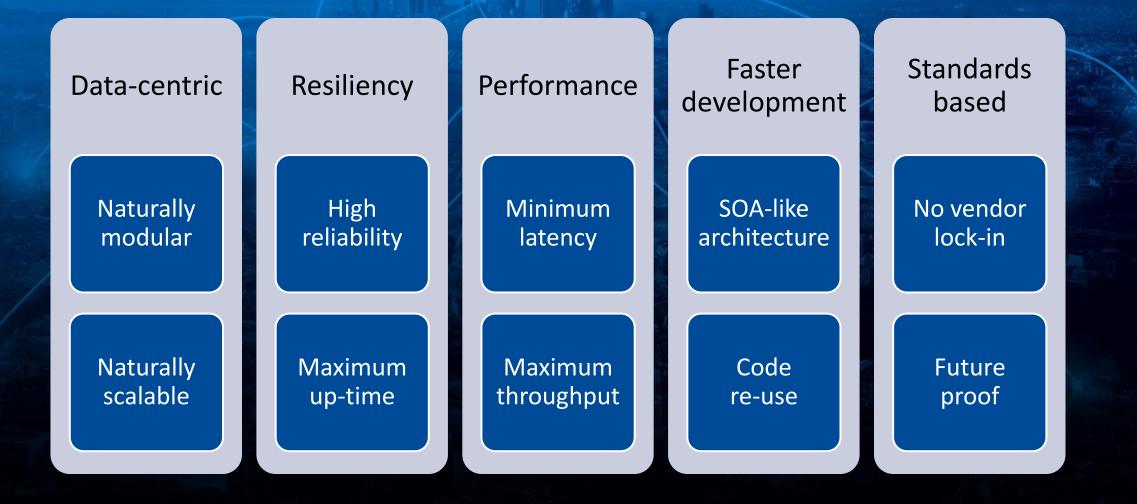


Enabling Interoperability through a Rich Automotive Ecosystem

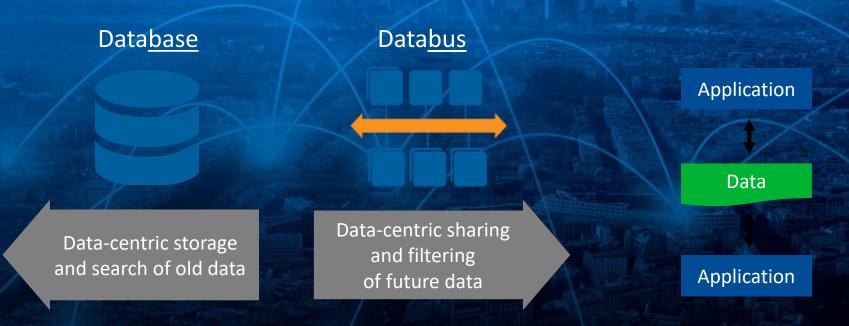


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Why DDS ?



Data-Centric Architectures



- Data Centricity Definition:
 - The interface is the data
 - The infrastructure understands that data
 - The system manages the data and imposes rules on how applications exchange data

Message-

Application

Application





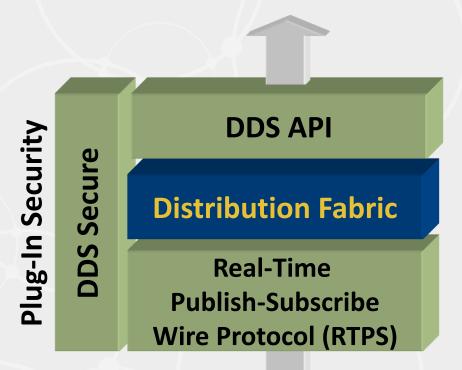




Cross-vendor portability

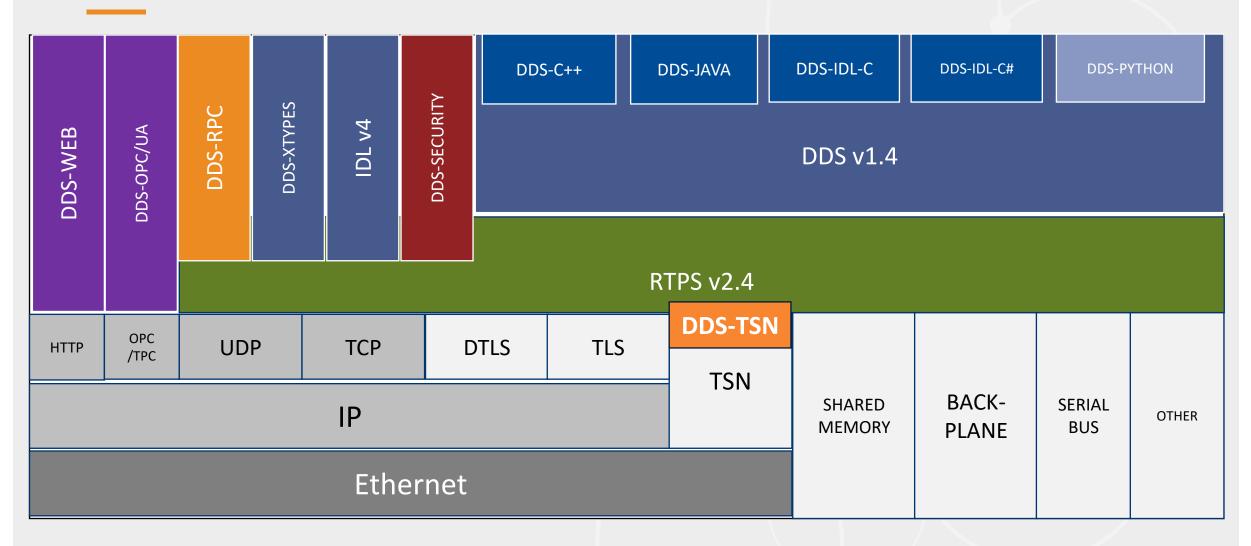
- Data Distribution Service
 https://www.dds-foundation.org/
- Freely downloadable OMG Standard:
 Covers API, protocol, security, TSN and more
- More than a dozen implementations

 Open-source and commercial
- Multiple language bindings
 C, C++/11, Python, Java, C#, Ada, Go, [Rust]
- Multi platform support
 - Windows, Linux, RTOS, iOS, Android, AUTOSAR, bare metal
- Safety-Cert versions are available



Cross-vendor interoperability

DDS Standard Covers:





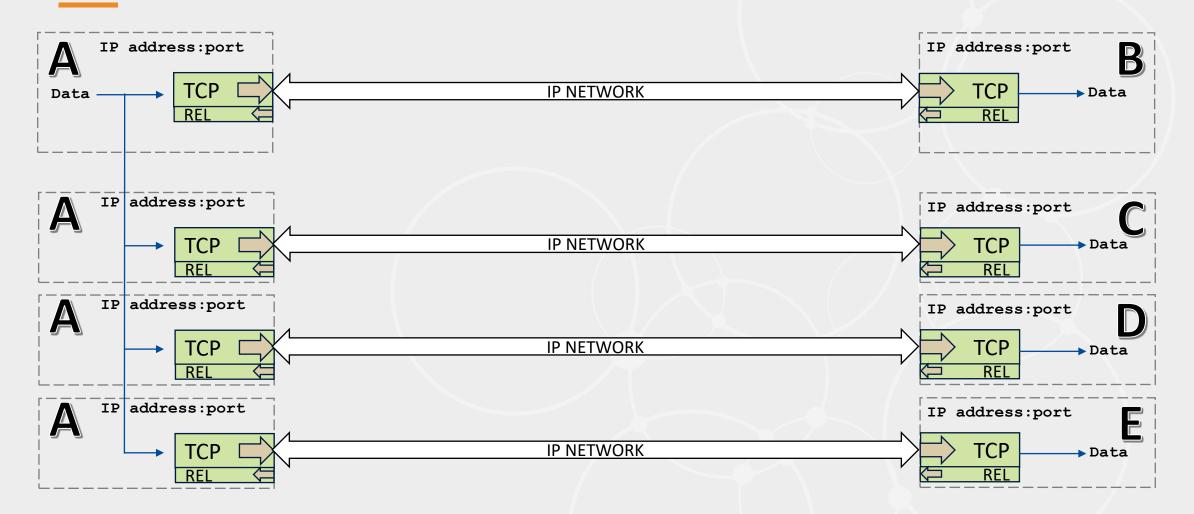
Data Communication, Middleware and DDS



Data Communications: UDP

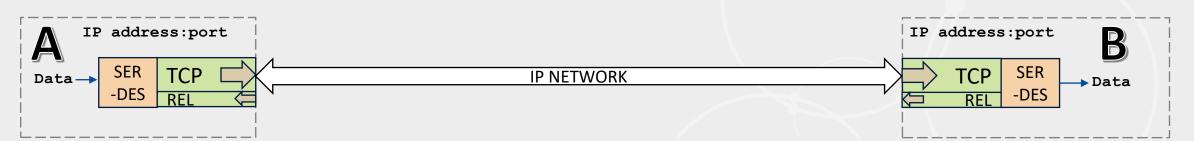


Data Communications: TCP



<u>rti</u>

Data Communications



+ Serializer / Deserializer: String(JSON, XML) or Binary

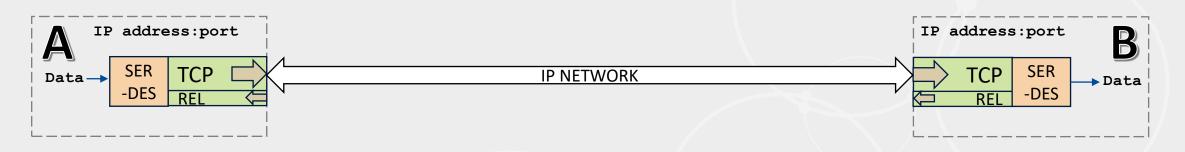
Common Ports

= Send data to any IP address and port number (0-65535)

Port Number	Service	Protcol	Port Number	Service	Protcol
20-21	FTP	tcp	1337	menandmice-dns	tcp
22	SSH	tcp	1194	OpenVPN	tcp/udp
23	Telnet	tcp/udp	1433-1434	Microsoft SQL	tcp/udp
25	SMTP	tcp	1701	L2TP	udp
43	whois	tcp	1723	MS PPTP	tcp
49	TACACS	tcp/udp	1725	MS PPTP	tcp
53	DNS	tcp/udp	1741	cisco-net-mgmt	tcp
67-68	DHCP/BOOTP	udp	1812-1813	RADIUS	udp
69	TFTP	udp	1985	HSRP	tcp
79	Finger	tcp	2000	Cisco SCCP	tcp/udp
80	HTTP	tcp	2002	Cisco ACS	tcp
82	xfer	tcp	2049	NFS	tcp
83	mit-ml-dev	tcp	2082-2083	cPanel	tcp
88	Kerberos	tcp	2100	Oracle XDB	tcp
110	0002	ton	7007	مان	ten

Evolving systems needed more routing capability

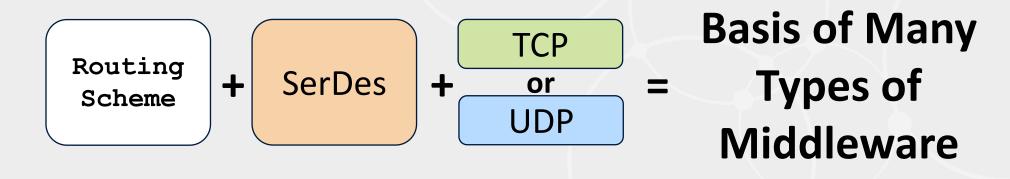
Routing Beyond Address & Port



+ Routing info in packet payload:

- URL: <u>www.rti.com/drive</u>
- TOPIC: vehicle/powertrain/range
- ID: [32-bit number]

(HTTP, WebSocket) (MQTT, DDS, NATS) (SOME/IP)



The Slippery Slope of Middleware

- Reliability
- Scalability
- Other transports (Shared Memory, Serial, Radio, ..)
- Security (Layered)
- Flow Control
- Redundancy & Failover
- Filtering (Time or Content)

- Performance (Time and Space)
- Liveliness
- Lifespan
- Discovery, PnP
- TSN
- Safety Certification
- Prog Language Support
- Interoperability

Bringing Data-centricity to Automotive

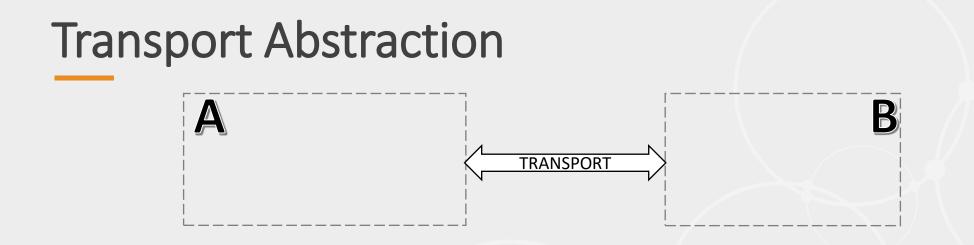


Wish List

• Reliability

- Any transport (even UDP multicast!)
- Fully tunable
- Discovery & Transports
 - No more IP address configuration
 - Any transport (even shared memory)
 - Zero-Copy support
- Safety and CyberSecurity
 - Any transport
 - Freely intermix secure & plaintext
- Scalability

- Advanced Capabilities
 - Redundancy & Failover
 - Time-based filtering
 - Content-based filtering
 - Latency Budget
 - Liveliness
 - Persistence & Durability
 - Recording & Replay
 - Hierarchical System Partitioning
 - Any OS / RTOS, CPU, Language
 - No vendor lock-in
- High Speed / Low Latency



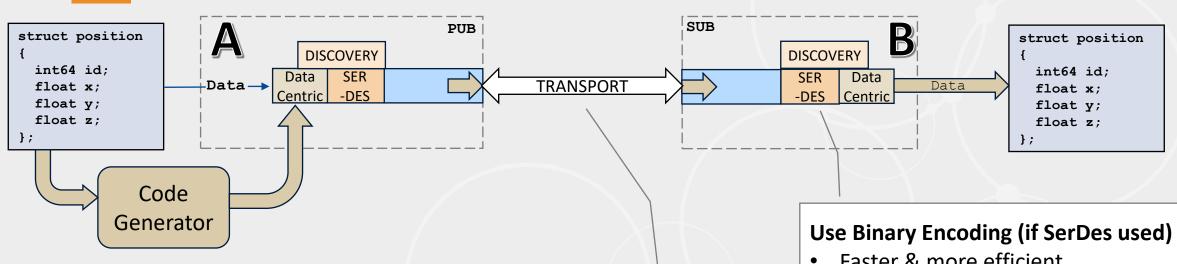
• Same API, regardless of which transport is used: IP Network, Shared Memory, Backplane, etc.

ISSUE: how do you resolve:

- "Send to 192.168.3.202:7105" (UDP)
- "Send to 0x81004acb20"

(Shared Memory)

Data-Centric Communications



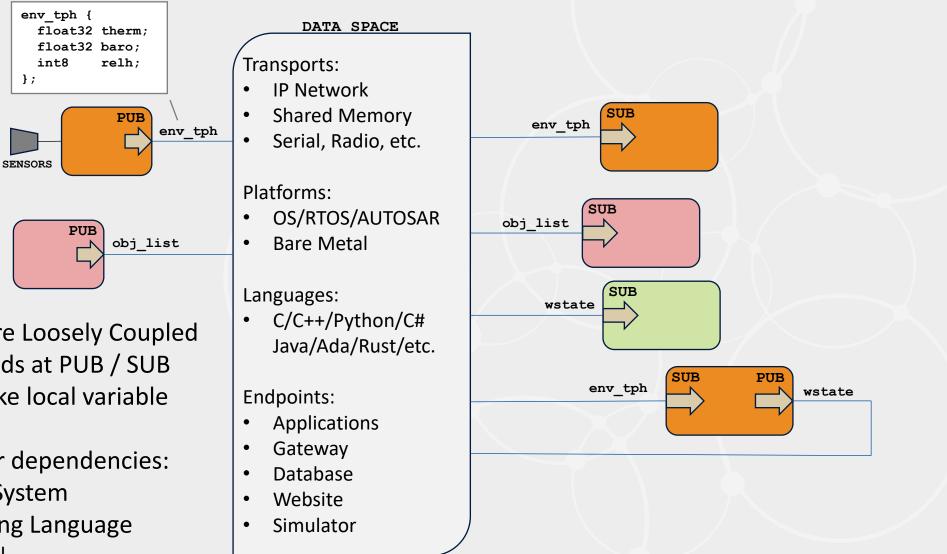
- Make it be Data-Centric
 - The data is the interface
 - Data appears as a local variable •
- Make it use Publish-Subscribe
 - Include RPC Support for SOA ٠
- Add a Discovery Mechanism

- Faster & more efficient
- Accommodates mixed endianness
- CDR (Common Data Representation) •

Use a Purpose-built Protocol

- Designed for pub/sub, discovery, and advanced capabilities.
- RTPS (Real Time Publish / Subscribe)

Data-Centric Communications



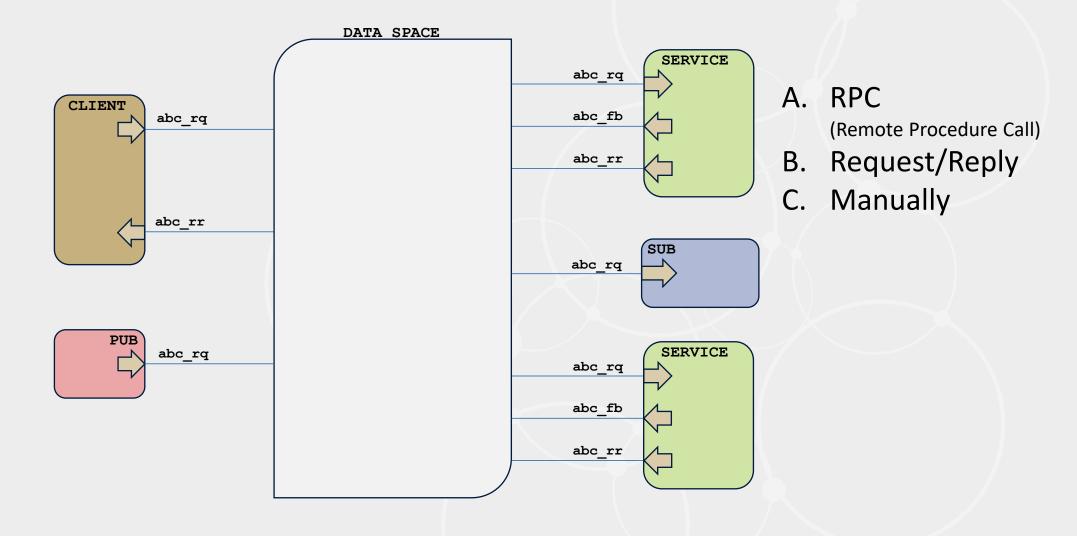
Applications are Loosely Coupled

- Concern ends at PUB / SUB
- Data acts like local variable

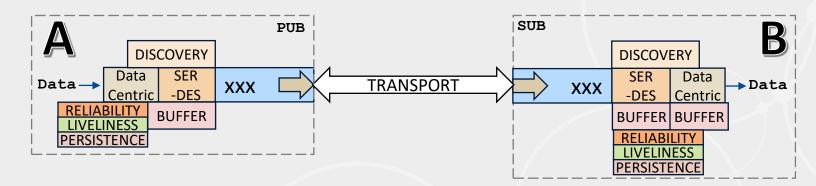
Removes other dependencies:

- **Operating System**
- **Programming Language**
- Platform / CPU

Data-Centric / Service Oriented



Improving Reliability



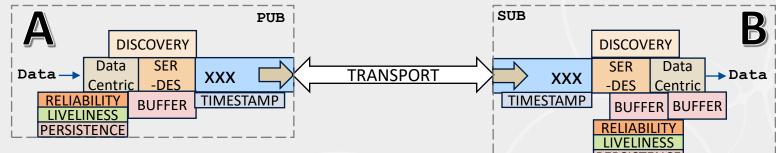
Add Data Buffers to Send and Receive

- Add a RELIABILITY Mechanism
 - Fully adjustable for difficult environments:
 - Rate, Time, Buffer level, App-level ACK
 - Guaranteed in-order delivery
 - Applies to all transports (including UDP multicast)
- Add LIVELINESS
 - Periodic message that says: "I'm still here"
 - For low-probability events and alarms

- Add a PERSISTENCE Function
 - Immediate 'catch-up' for Late-Joiners
 - Restore state after power-cycle (Durability)



Time-Based Improvements



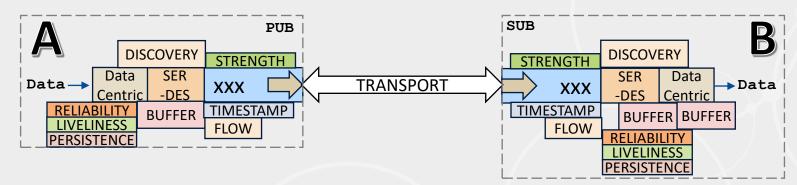
Add TIMESTAMP function

Timestamp data at send and receive Enables:

- Time-based filter
 - Pub at 100Hz, Sub at 5Hz
- Lifespan
 - Reject samples that are older than 3mS
- Publication-order delivery
 - Many publishers on same topic

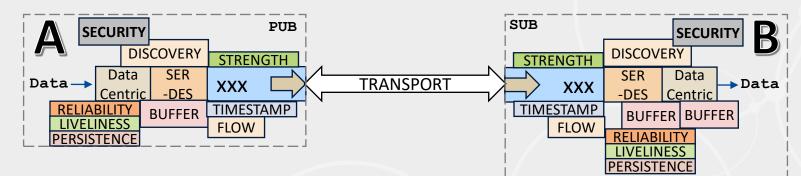


Redundancy and Flow Control



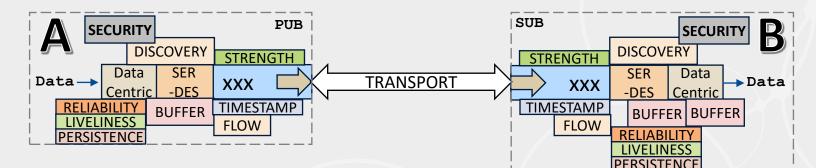
- Add STRENGTH
 - Redundant components with automatic failover
 - Zero-downtime maintenance and upgrades.
- Add BATCHING, ASYNC PUB, FLOW CONTROL
 - Batch smaller samples together for publication
 - Send very large samples in sections
 - Regulate the flow of high-volume transient data.

Safety and Security



- Add SECURITY (per-dataflow)
 - Separate Encryption, Authentication, Access Control
 - Freely intermix secure & plaintext data flows
 - Maintenance, Configuration, Customer Info, Updates
 - Allows simultaneous openness and protection in a system
- Create a Safety-Certifiable Version, to:
 - ISO 26262 ASIL-D
 - DO-178C Level A

Working with Data Types

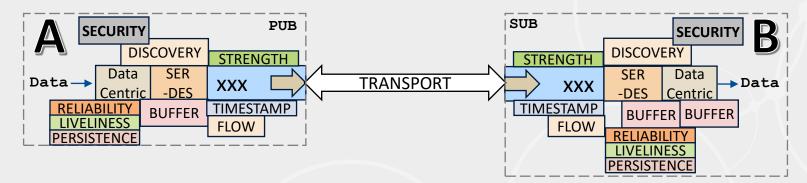


- Add TYPE AWARENESS
 - Enables Content-based filtering
- Add KEYED TYPE SUPPORT
 - Enables large Scalability
- Add TYPE EXTENSIBILITY
 - Enables types to change while maintaining compatibility with previous versions.

struct position
{ @key
 int64 id;
 float x;
 float y;
 float z;
 float w;
};



Stopping Point



The preceding describes a portion of what's inside DDS

- Note that these improvements largely avoid the data path
 - Very high performance / low latency
- This is code that you don't have to write or maintain.

DDS acts like a 'data teleporter' Now let's see how this can be used...

Data-Centric Design and Use Patterns



Remember: It's Just Data!

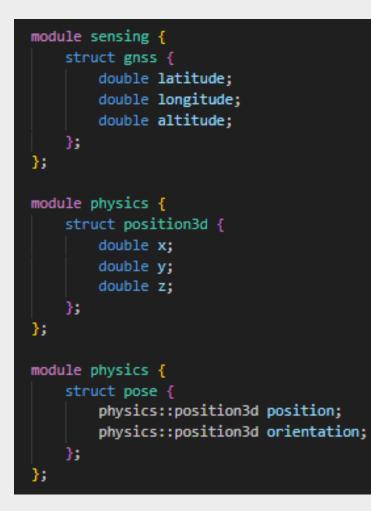
How many things can be done with Data?

- Send & Receive
- Record & Replay
- Filter
- Convert
- Emulate
- Simulate
- Enqueue
- Analyze
- Visualize

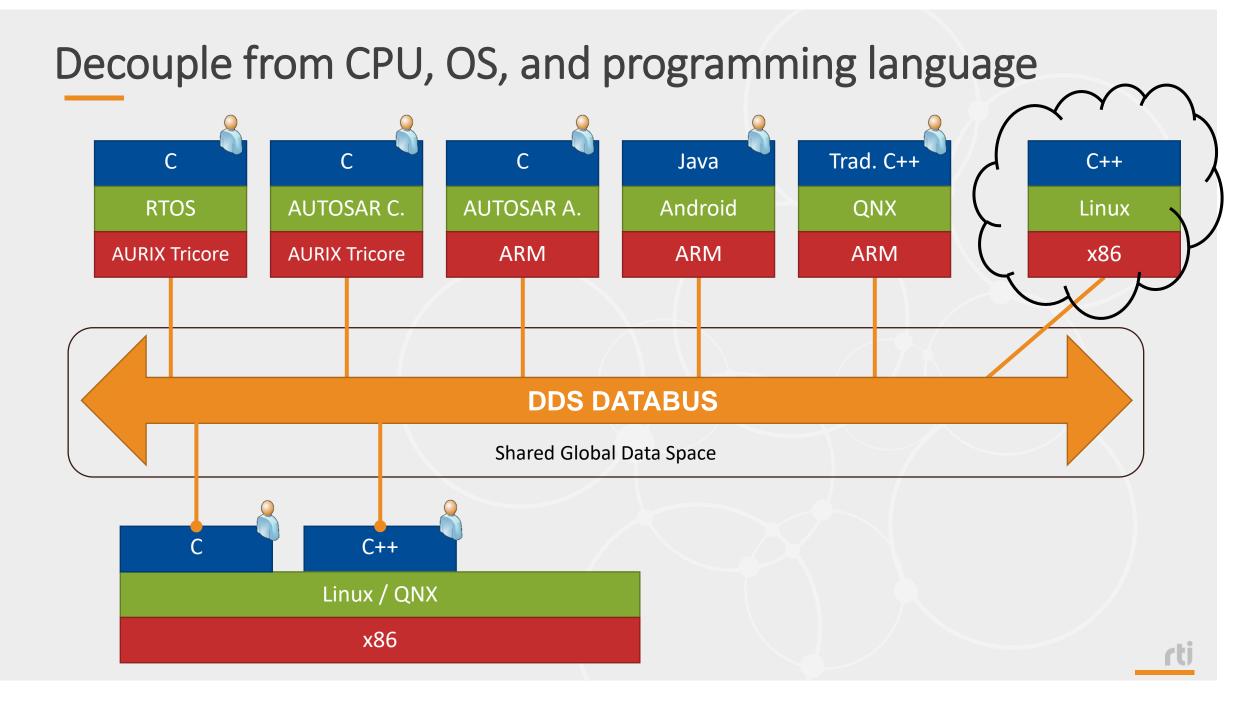
- Combine
- Extend
- Transform
- Duplicate
- Discover
- Describe

... independently from the hardware or teams

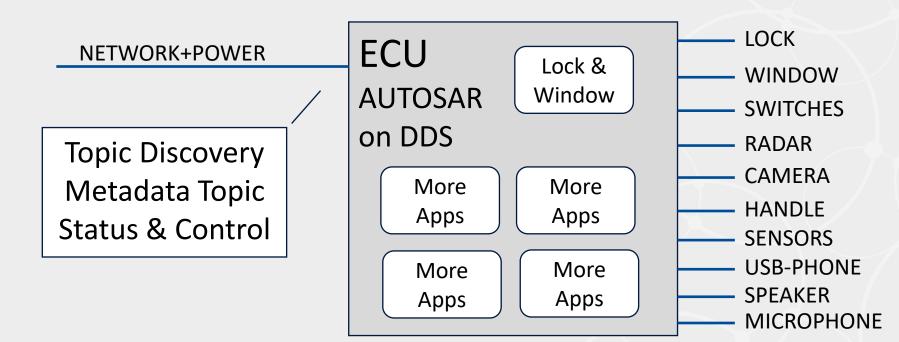
Data Type Examples



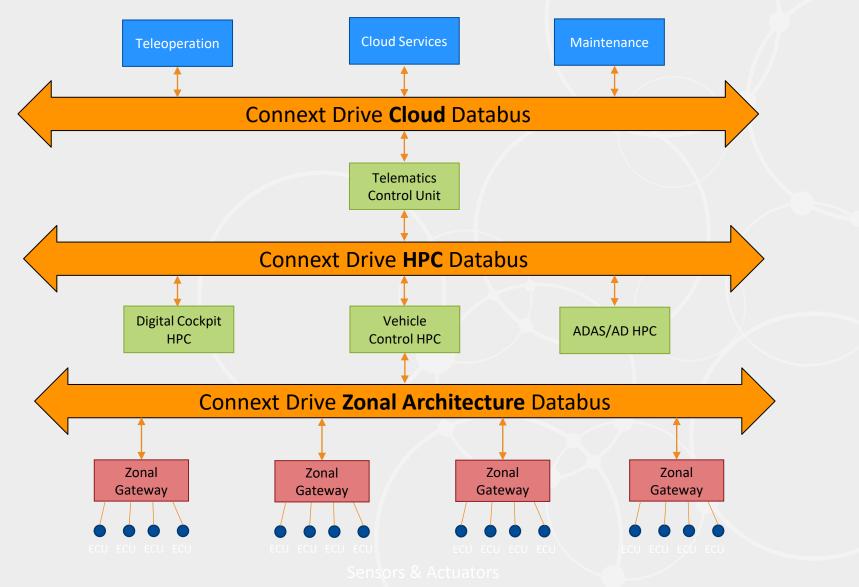
- Group members by use pattern
- Create reusable type definitions (reduces discovery content)
- Align types with other needs (such as with COVESA VSS)
- Types are defined in IDL or XML & sent to code generator
- Types are instantiated as named Data Topics in DDS



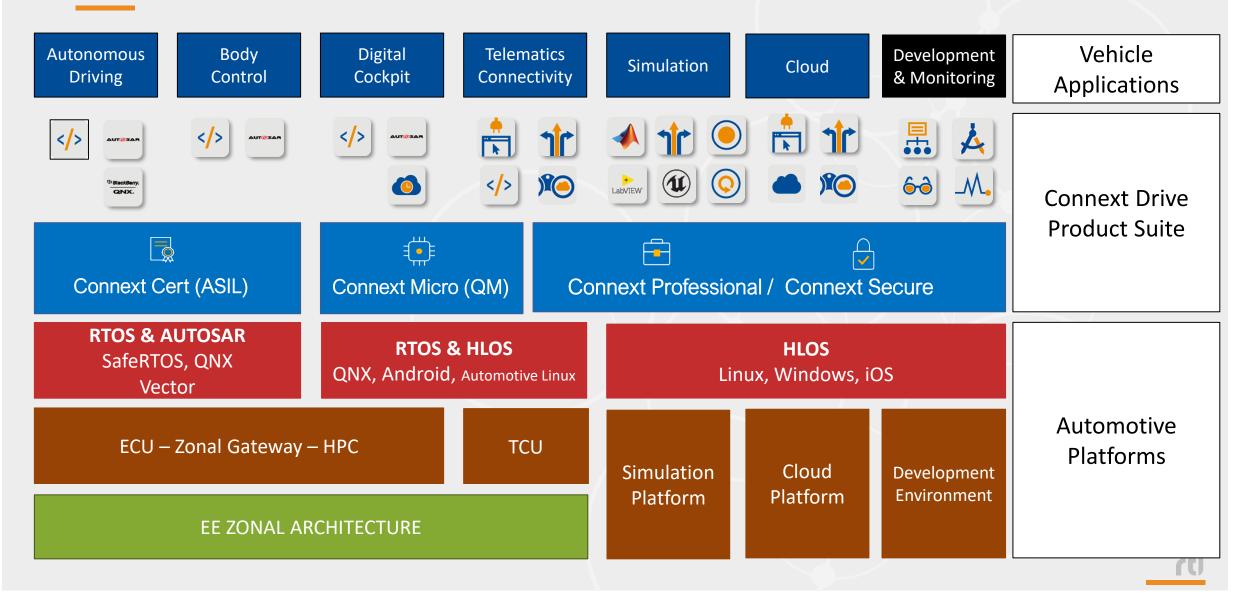
Configuration Flexibility and Cable Reduction



Connext Drive® Automotive Grade Framework



Connext Drive® Automotive Architecture



Data-Centric Ecosystems



Data Centric Ecosystems need Common Data Types

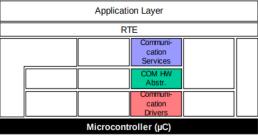
Ecosystems of independently developed yet fully interoperable tools and functional modules, built on top of DDS and using common data models:



AUTOSAR DDS Integration

Δυτοςδαr

Architecture – Content of Software Layers **Communication Stack – DDS** Example: Communication Services Generic NM Interface Ethernet UDP NM Manager PDU Router Socket Adaptor TCP/IP Communication Services Task: Communication Hardware Abstraction Ethernet Interface Ethernet Switch Driver Ethernet Transceiver Drive **VO Drivers** Communication Drivers Ethernet Driver DIO Driver Handler / Driver > QoS handling μC Ethernet MI External Ethernet Controller



The Data Distribution Services is a module for data-oriented vehicle network communication.

Provide the DDS standard interfaces.

The DDS module supports:

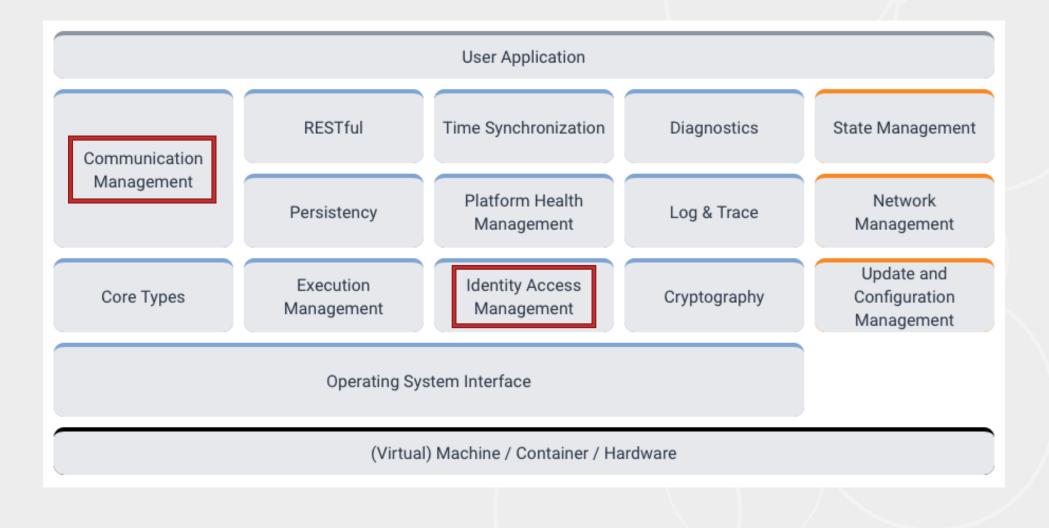
- Signal Base Publisher/Subscriber communication path
- Full static configuration

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AUTOSAR DDS Integration





What is ROS? (Robot Operating System) **ICOLS**

COMMUNITY

ROSCon Seo

ROSCon Madri

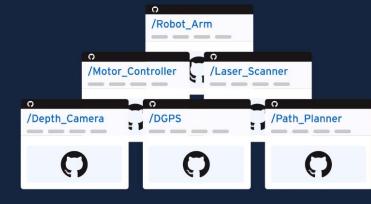
PACKAGES

DOWNLOADED 500,000,000+ ROS PACKAGES

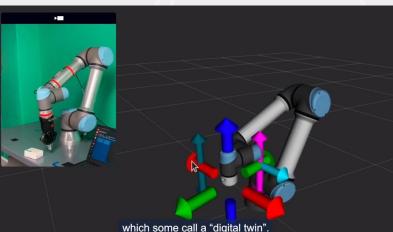
and have downloaded over half a billion ROS packages in 2020 alone.

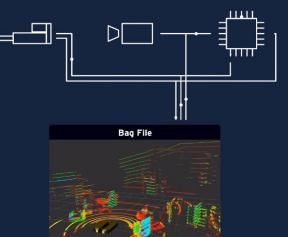


This community is supported by the ROS Technical Stee



ROS's modular architecture allows developers to build robots free Messages can be easily sent to a variety of visualization and from vendor lock in or licensing fees. teleoperation tools.





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Data Centric Ecosystems need Common Data Types



COVESA: VSS

- Catalog of defined signals
- Enables an off-vehicle ecosystem of tools and services

Can COVESA do more?

- Define a catalog of data types for invehicle use (major module boundaries).
- Aligned with present VSS
- Provide a reference implementation including a VSS gateway

Takeaways



Benefits of DDS

- Extreme Performance
- Developer Efficiency
- Code reusability
- Extensive QoS
- Open Standard / Multi-sourced / Field-proven
- Standardized for AUTOSAR and more
- Thriving ecosystem
- Ideal framework for integration and autonomy
- Conceptually easy to understand

Thank You!!



Thank you!





K

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f

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