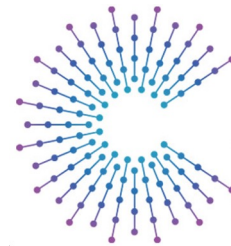




Empowering digital services

VISS API towards Android Automotive OS

AMM April 2024 in Gothenburg



COVESA

Accelerating the future of connected vehicles

Speakers



Emil Dautovic



Ulf Björkengren



Peter Winzell



Renjith Rajagopal



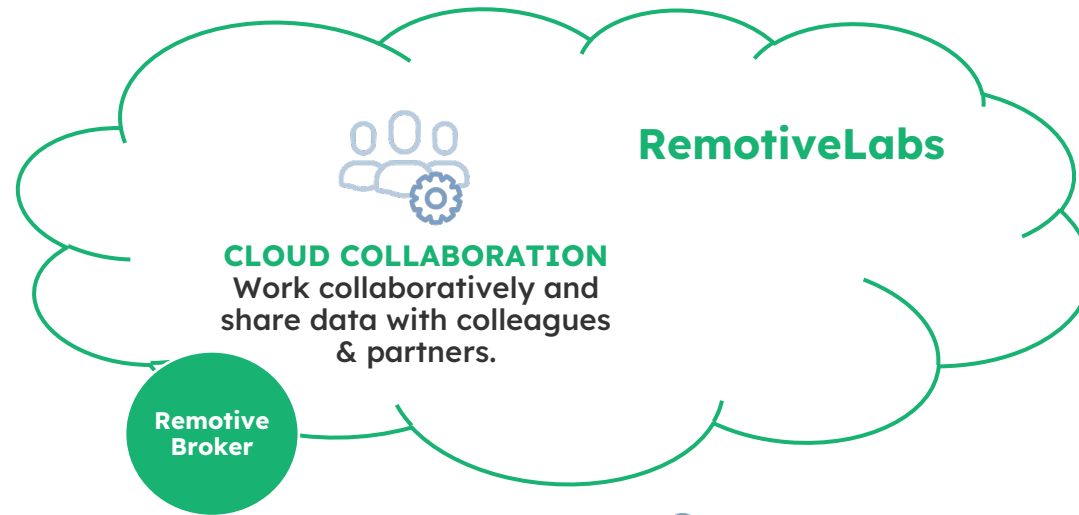
Kristoffer Nilsson



Things to solve

- Enable access to signals from a vehicle - both Android, no need for slow recompile, and non-Android
- Easy to add new use case - e.g. insurance that need access to new data for driver behavior

The different pieces of the puzzle

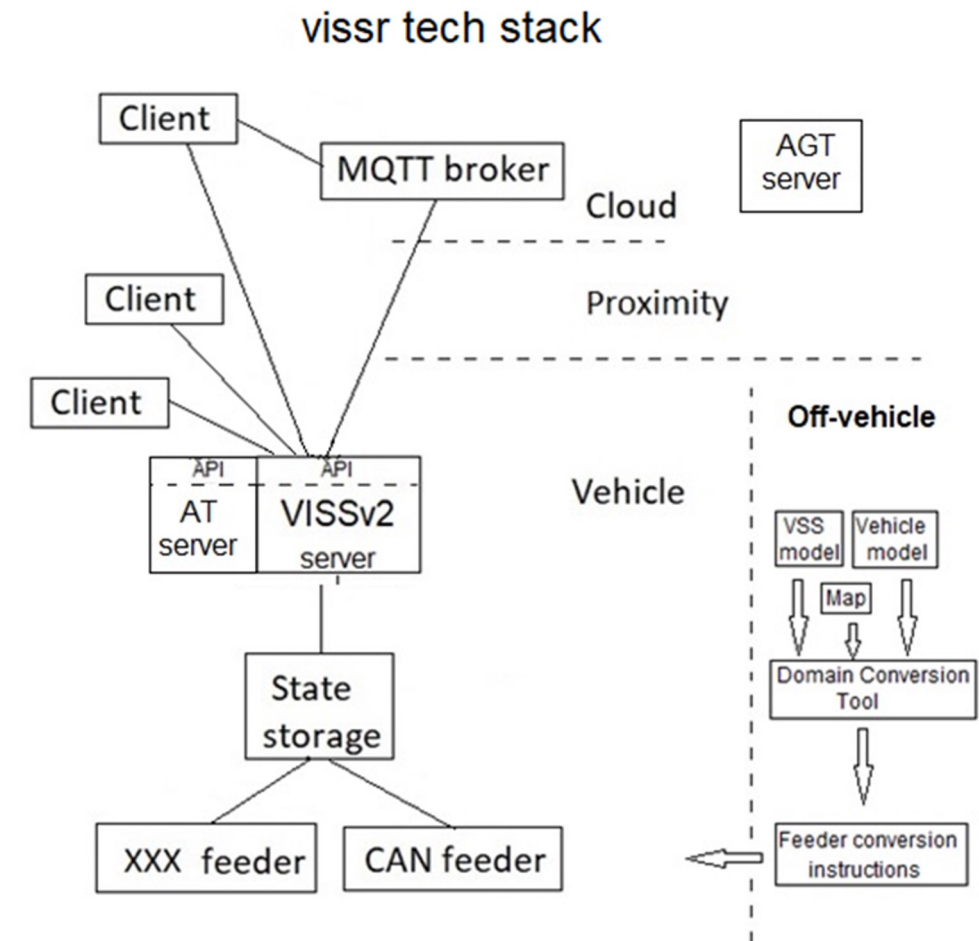


VISS reference implementation overview

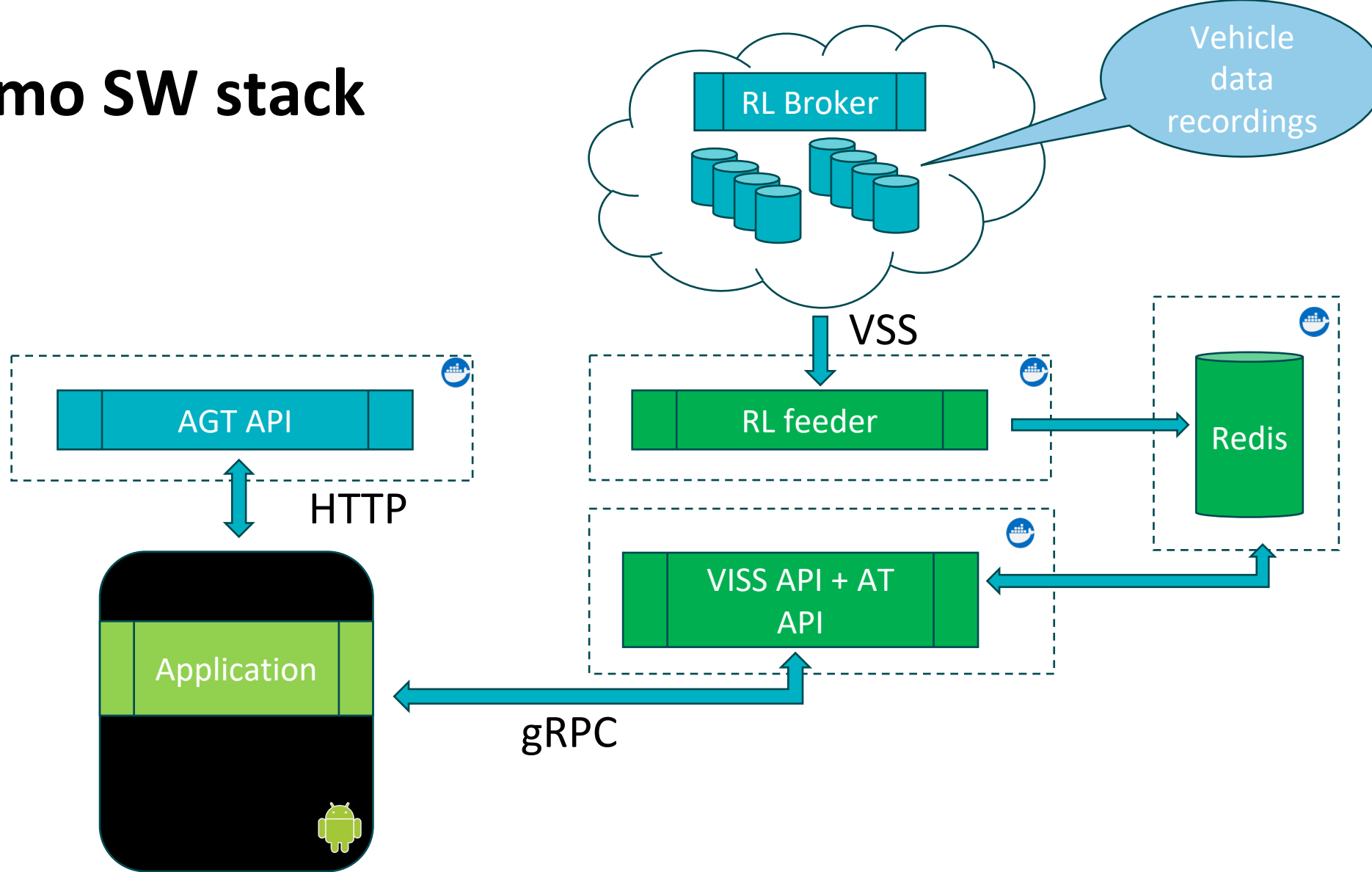
- The Vehicle Information Service Specification development was started at W3C
 - <https://github.com/w3c/automotive>
- Where it was discontinued and in March 2024 migrated to
 - <https://github.com/COVESA/vehicle-information-service-specification>
- VISSv2 features
 - Supported transport protocols: HTTP / Websocket / MQTT
 - Methods: Get / Set / Subscribe (Unsubscribe)
 - Subscription filters: Timebased / Change / Range / Paths / Curve logging / History
 - Access control: Token based, OAuth2 inspired, RBAC support, single node granularity
 - Consent support: Obtaining consent delegated to an External Consent Framework, acts as firewall

VISS reference implementation overview

- The VISS reference implementation (visr) is after migration found at
 - <https://github.com/COVESA/visr>
- visr features
 - Complete VISSv2 feature support, plus
 - gRPC
 - SwCs to realize a complete tech stack:
 - Data store: SQLite / Redis / IoTDB / ..
 - Feeder: Template where only the vehicle interface client needs implementation / RL-feeder / EVIC-feeder / ...
 - Client: JS based: AGT, AT, HTTP, WS, integrated access control,... / Go-based: MQTT, curve log to CSV file, ...
 - Domain Mapping Tool: creates feeder conversion instructions from YAML input

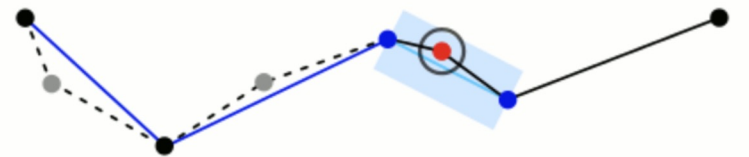
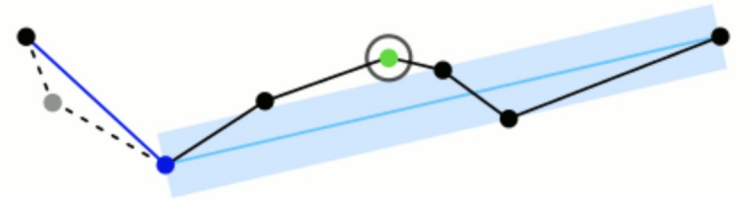


Demo SW stack



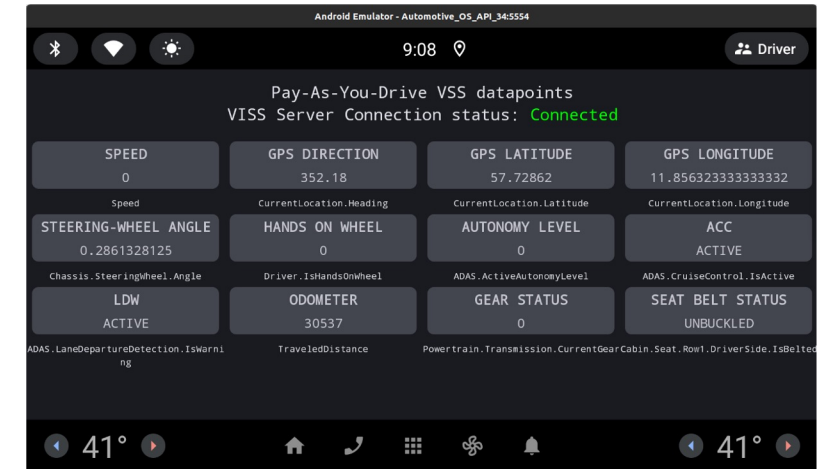
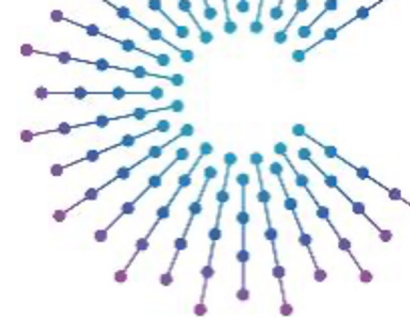
Curve logging

- A method of moving data efficiently from vehicle to server.
- The purpose of the algorithm is to identify useless points and discard them while preserving the most important information.
- It keeps checking the points of maximum error. If the difference between the predicted and actual position is significant, the points are sent. Throw away the points that, essentially, were not carrying any useful information
- Method developed by GeoTab (based on the [Ramer-Douglas-Peucker algorithm](#)).
Now part of the VISSv2 specification



Demo content

- Use case : “How could an OEM enable access to certain Vehicle datasets to digital partner that want to accurately calculate Safety Scores based on driving behavior”
 - Safety Score Android application/service- Runs on AAOS generic emulator
 - Request AG token(HTTP) - Authentication/Authorisation
 - Request AT token with AG token(HTTP) - Validate access
 - Subscribe Multiple VSS data with AT token(gRPC)
 - VISS + AT server - Runs on local host PC as docker container
 - VSS datasets tagged with ‘validate’ attribute with access-control mode - “read-write”
 - AGT server - Runs on Local host as docker container
 - Authentication & Authorisation of client
 - RemoteLabs virtual sensor cloud - Runs on cloud
 - Pre-recorded real vehicle datasets collected from Volvo XC90 PHEV





Demo time



SimpleScreenRecorder

Recording

Pause recording

Enable recording hotkey Enable sound notifications

Hotkey: Ctrl + Shift + Alt + Super + **R**

Information

Total time: 0:00:00
 FPS in: 0.00
 FPS out: 0.00
 Size in: 2560x1440
 Size out: ?
 File name: ?
 File size: 0 B
 Bit rate: 0 bit/s

Preview

Preview frame rate: 10

Note: Previewing requires extra CPU time (especially at high frame rates).

Start preview

Log

```
[X11Input:InputThread] Input thread started.  

[PulseAudioInput:InputThread] Stream is a monitor.  

[PageRecord:StartInput] Started input.  

[PulseAudioInput:InputThread] Input thread started.
```

Recording based on rec_vctech_wholefoods.zip
1 file(s)

avinew_001.log
1 file(s)

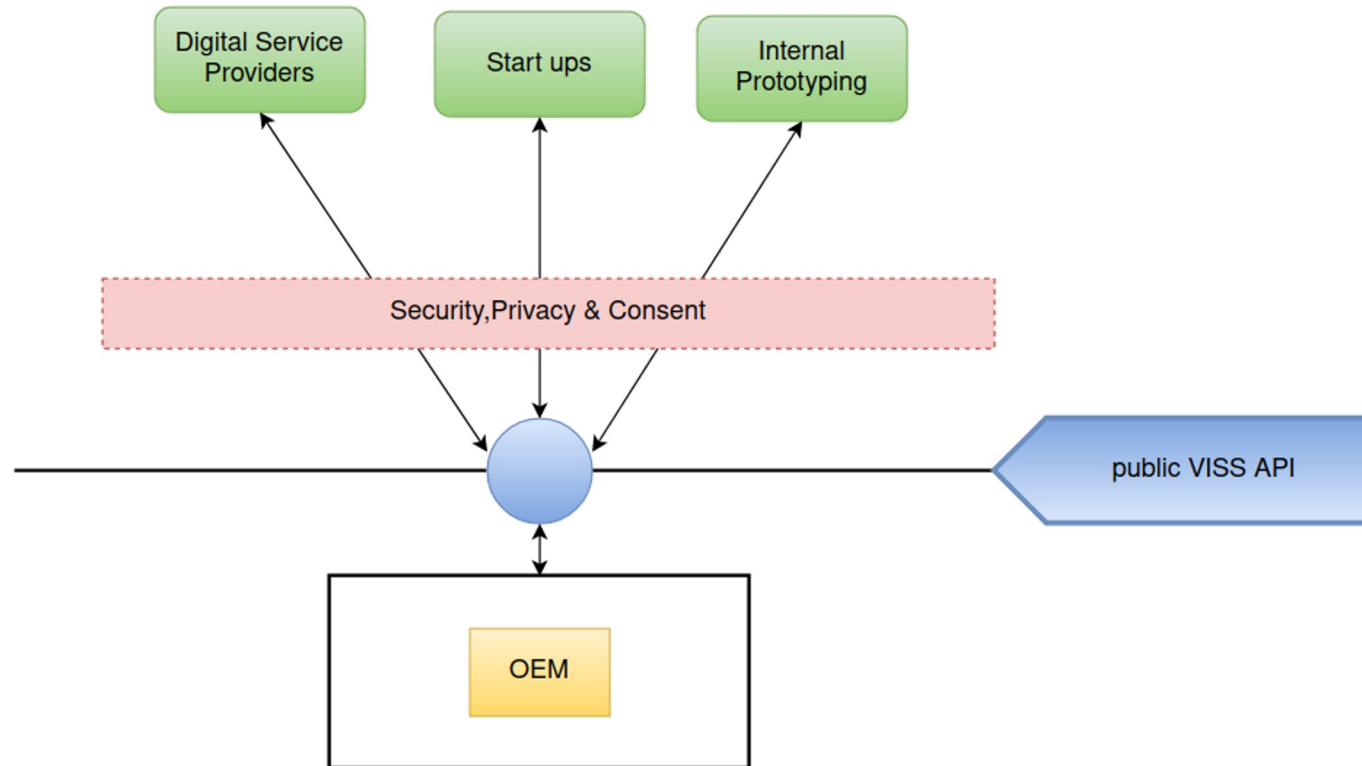
Drag a file here or click to upload a recording

>	Uploaded	2024-03-22 14:40	
>	Uploaded	2023-03-07 14:49	
>	Uploaded	2022-12-29 15:14	
>	Uploaded	2022-12-07 10:50	
>	Uploaded	2022-12-02 15:10	
>	Uploaded	2022-11-30 13:48	
>	Uploaded	2022-11-30 12:52	
>	Uploaded	2022-11-03 12:24	
>	Uploaded	2022-09-30 20:26	
>	Uploaded	2022-09-16 12:11	
>	Uploaded	2022-09-02 09:44	
>	Uploaded	2022-08-22 10:04	
>	Uploaded	2022-08-22 10:03	

CLI Hints

Conclusion

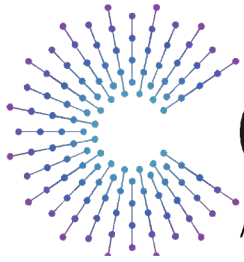
- An expansive, reputable & industry adopted Open Vehicle API ecosystem that respects Security, Privacy & Consent beckons new thinkings & fosters innovations.



References

More interesting stuff at:

- Sign up for free and test at <https://cloud.remotivelabs.com/>
- The VISS specification at [VISS version 2 - Core \(w3.org\)](#) , [VISS version 2-Transport \(w3.org\)](#)
- The VISS reference implementation at <https://github.com/COVESA/vissr>
- Reference android application at [Android application](#)
- GeoTab curve logging at [curve logging](#)



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Thank you for your attention

